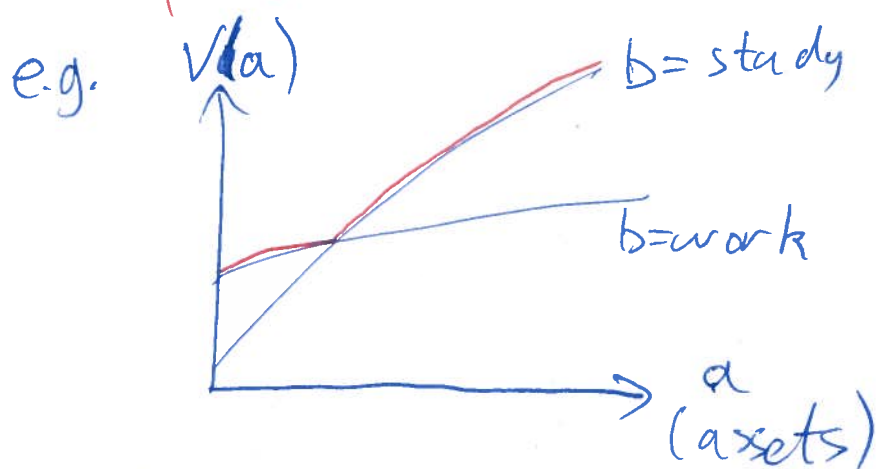


2.3 Envelope theorem, etc.

Economically speaking:

$$V(a) = \max_b v(a, b) = v(a, b(a))$$

$V(a)$: value function
 a : state variable
 b : choice variable
 $v(a, b)$: objective function
 $b(a)$: policy function



Goal: study relationship between marginal values $V'(a)$ and optimal choices $b(a)$.



The red curve envelopes ("surrounds") the blue lines. The red curve is called the "upper envelope".

High school geometry: if two curves touch without crossing, then they are tangent (i.e. have the same slope, and are parallel).

Theorem 2.1 (Envelope theorem)

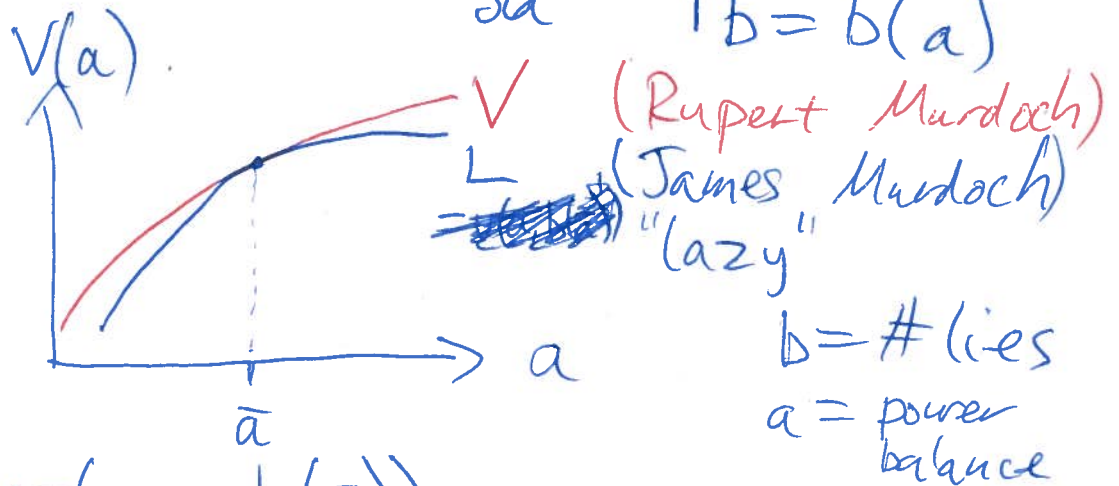
Let $v: \mathbb{R}^n \times \mathbb{R}^m \rightarrow \mathbb{R}$ be a differentiable,
 $\begin{matrix} a \\ \text{(states)} \end{matrix}$ $\begin{matrix} b \\ \text{(choices)} \end{matrix}$

$V(a) = \max_{b \in \mathbb{R}^m} v(a, b)$ be its value function
and $b(a)$ be its policy function.

If v is a differentiable function,

then $V'(a) = \left. \frac{\partial v(a, b)}{\partial a} \right|_{b=b(a)}$

Proof:



let $L(a) = v(a, \underbrace{b(\bar{a})}_{\text{"final words"}})$.

Since $b(\bar{a})$ is inferior to $b(a)$ at state a ,
(i.e. $v(a, b(\bar{a})) \leq v(a, b(a))$)

we know ~~we~~ $L(a) \leq V(a)$, for all a .

We also know $L(\bar{a}) = V(\bar{a})$. Therefore

$V(a) - L(a)$ is minimised at \bar{a} . At
the minimum, the first-order condition

$$V'(\bar{a}) - L'(\bar{a}) = 0 \text{ holds, } \Leftrightarrow V'(\bar{a}) = L'(\bar{a}).$$

where $L'(\bar{a}) = \left. \frac{\partial v(a, b)}{\partial a} \right|_{b=b(\bar{a})}$. \square

Proof (chain rule):

$$v(a) = v(a, b(a)).$$

Chain rule says:

$$v'(a) = \underbrace{\frac{\partial v(a, b)}{\partial a} \Big|_{b=b(a)}}_{\text{direct effect}} + \underbrace{\frac{\partial v(a, b)}{\partial b} \Big|_{b=b(a)}}_{\text{indirect effect}} b'(a)$$

$$FOC \Rightarrow 0$$

Detour: vector calculus

Consider $h(x) = f(g(x))$,

where $g: \mathbb{R} \rightarrow \mathbb{R}^2$, ~~and~~ $f: \mathbb{R}^2 \rightarrow \mathbb{R}$

Chain rule: $h'(x) = f'(g(x)) g'(x)$.

$$= \begin{bmatrix} \frac{\partial f}{\partial y_1} & \frac{\partial f}{\partial y_2} \end{bmatrix} \begin{bmatrix} \frac{\partial g_1}{\partial x} \\ \frac{\partial g_2}{\partial x} \end{bmatrix}$$

$$= \frac{\partial f}{\partial y_1} \frac{\partial g_1}{\partial x} + \frac{\partial f}{\partial y_2} \frac{\partial g_2}{\partial x}$$

Link to envelope theorem:

~~at~~ $x=a$, $h(x) = v(a)$, $g(x) = \begin{bmatrix} a \\ b(a) \end{bmatrix}$, ~~and~~

~~y =~~ $y = \begin{bmatrix} a \\ b \end{bmatrix}$, $f(y) = v(a, b)$, $f(g(x)) = v(a, b(a))$

Since $b(a)$ is an optimal choice at a , we know the first-order conditions

$$\frac{\partial v(a, b)}{\partial b} \Big|_{b=b(a)} = 0.$$

Therefore the second term vanishes and the formula we wanted is left over. \square

Example: l workers
 w wage

Profits:

$$\pi(w) = \max_l 10\sqrt{l} - wl.$$

Want to calculate $\pi'(w)$.

With envelope theorem:

$$\begin{aligned}\pi'(w) &= \left[\frac{\partial}{\partial w} [10\sqrt{l} - wl] \right]_{l=l(w)} \\ &= [-l]_{l=l(w)} \\ &= -l(w).\end{aligned}$$

Without the envelope theorem:

~~Reformulate~~ Reformulate $\pi(w) = 10\sqrt{l(w)} - w l(w)$
and differentiate

$$\begin{aligned}\pi'(w) &= 10 \cdot \frac{1}{2} \frac{1}{\sqrt{l(w)}} \cdot l'(w) - l(w) - w l'(w) \\ &= 5 \frac{l'(w)}{\sqrt{l(w)}} - l(w) - w l'(w).\end{aligned}$$

What a mess!

To calculate $l(w)$, we take the FOC

$$\frac{\partial}{\partial l} [10\sqrt{l} - wl] = 0$$

$$\Leftrightarrow 10 \cdot \frac{1}{2} \cdot \frac{1}{\sqrt{l}} - w = 0$$

$$\Leftrightarrow \frac{5}{\sqrt{l}} = w$$

$$\begin{aligned}\Leftrightarrow \sqrt{l} &= \frac{5}{w} \\ \Leftrightarrow l(w) &= \frac{25}{w^2}.\end{aligned}$$

$$l'(w) = - \frac{50}{w^3}$$

Substituting into

$$\pi'(w) = 5 \frac{l'(w)}{\sqrt{l(w)}} - l(w) - w l'(w)$$

$$= 5 \frac{l'(w)}{\left(\frac{5}{w}\right)} - \frac{25}{w^2} - w l'(w)$$

$$= \cancel{w l'(w)} - \frac{25}{w^2} - \cancel{w l'(w)}$$

$$= - \frac{25}{w^2} = - l(w). \quad \square$$

Recall the firm's problem,

$$\pi(p; w) = \max_{x \in \mathbb{R}_+^{N-1}} p f(x) - w \cdot x$$

Applying the envelope theorem gives:

$$\begin{aligned} \frac{\partial \pi(p; w)}{\partial p} &= \left[\frac{\partial}{\partial p} \{ p f(x) - w \cdot x \} \right]_{x=x(p; w)} \\ &= [f(x)]_{x=x(p; w)} \\ &= f(x(p; w)) = \underbrace{y(p; w)}_{\text{output quantity}}. \end{aligned}$$

$$\begin{aligned} \frac{\partial \pi(p; w)}{\partial w_i} &= \left[\frac{\partial}{\partial w_i} \{ p f(x) - w \cdot x \} \right]_{x=x(p; w)} \\ &= [-x_i]_{x=x(p; w)} \\ &= -x_i(p; w). \end{aligned}$$

Differentiating again gives

$$\frac{\partial^2 \pi(p; w)}{\partial p^2} = \frac{\partial y(p; w)}{\partial p}$$

$$\frac{\partial^2 \pi(p; w)}{\partial w_i \partial w_j} = - \frac{\partial x_i(p; w)}{\partial w_j}$$

eg: i = doctors
 j = nurses

$$= - \frac{\partial x_j(p; w)}{\partial w_i}$$

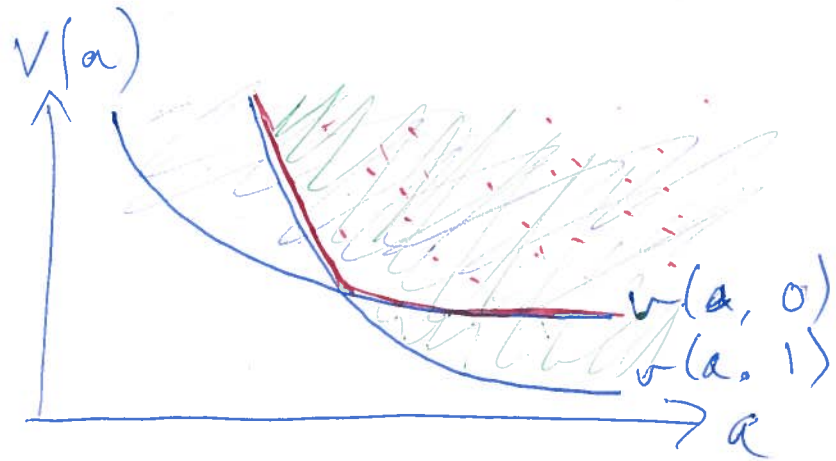
Assuming π is twice differentiable.

Theorem 2.2 Suppose $V(a) = \max_b v(a, b)$

where each $v(\cdot, b)$ is a convex function. Then V is a convex function.

Proof





Geometric idea:



Assume  convex hyper($v(\cdot, 0)$)

 convex hyper($v(\cdot, 1)$)

Want to prove  convex hyper(V)

Since  \cap  = , and the intersection of convex sets is convex, we conclude  (hyper(V)) is a convex set. Therefore V is a convex function. \square

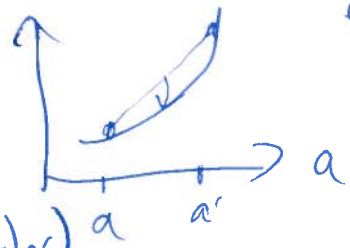
Proof (algebraic):

We would like to show

$$\underbrace{tV(a) + (1-t)V(a')}_{\text{line}} \geq \underbrace{V(ta + (1-t)a')}_{\text{curve}}$$

line

curve



$$\begin{aligned}
& tV(a) + (1-t)V(a') \\
&= t v(a, b(a)) + (1-t)v(a', b(a')) \\
&\geq t v(a, \underbrace{b(ta + (1-t)a')}_{\substack{\text{right choice} \\ \text{for wrong state}}}) + (1-t)v(a', b(a')) \\
&\geq t v(a, b(ta + (1-t)a')) + (1-t)v(a', \underbrace{b(ta + (1-t)a')}_{\substack{\text{right choice for} \\ \text{the same wrong} \\ \text{state}}}) \\
&\geq v(ta + (1-t)a', b(ta + (1-t)a')) \\
&\quad \text{since both points are on the} \\
&\quad \text{same curve, and we assumed} \\
&\quad \text{each curve (for each choice) is} \\
&\quad \text{a ~~function~~ convex function} \\
&= V(ta + (1-t)a'). \quad \square
\end{aligned}$$

Theorem 2.3 For every production f , the firm's profit function π is a convex function. Hence if π is smooth, then

$$\frac{\partial \pi(p; w)}{\partial p} \geq 0 \quad \text{and} \quad \frac{\partial x_i(p; w)}{\partial w_i} \leq 0$$

Proof Step 1: π is convex:

For each input choice $x \in \mathbb{R}_+^{N-1}$, the ~~for~~ objective function

$$(p; w) \mapsto p f(x) - w \cdot x$$

is a linear (and hence convex) function.

Therefore, π is the upper envelope of a set of convex functions, so Theorem 2.2 establishes that π is a convex function

Step 2: By the envelope theorem, we previously established that

$$\frac{\partial \pi(p; w)}{\partial p} = y(p; w),$$

and
$$\frac{\partial^2 \pi(p; w)}{\partial p^2} = \frac{\partial y(p; w)}{\partial p}.$$

Since π is a convex function,

$$\text{LHS} \geq 0.$$

So RHS ≥ 0 , i.e.

$$\frac{\partial y(p; w)}{\partial p} \geq 0. \quad \square$$

Note: only works if we diff'ate w.r.t. the same variable twice.

Lessons:

- * envelope theorem - how to differentiate value functions
- * env. theorem told us: marginal values are related to optimal choices
- * even without convexity assumptions on the production function, we established that the profit function is convex.
- * We established the input choices are decreasing in their corresponding prices, and output is increasing in the output price.

2.4 Cost functions and Dynamic Programming

Recall

$$\pi(p; w) = \max_{x \in \mathbb{R}_+^{N-1}} pf(x) - w \cdot x.$$

$$\pi(p; w) = \max_{y \in \mathbb{R}_+} py - c(y; w)$$

Bellman equation \rightarrow

$$\text{where } c(y; w) = \min_{x \in \mathbb{R}_+^{N-1}} w \cdot x$$

cost function s.t. $f(x) \geq y$.
 \leftarrow meet + prod. target

Lemma 2.1 (Principle of Optimality)

$$\begin{aligned}
 & \max_{x \in \mathbb{R}_+^{N-1}} p f(x) - w \cdot x \\
 &= \max_{y \in \mathbb{R}_+, x \in \mathbb{R}_+^{N-1}} p f(x) - w \cdot x \\
 & \quad \text{s.t. } f(x) = y \\
 &= \max_{y \in \mathbb{R}_+} \left(\max_{x \in \mathbb{R}_+^{N-1}} p f(x) - w \cdot x \right) \\
 & \quad \text{s.t. } f(x) = y
 \end{aligned}$$

Special case of:

$$\begin{aligned}
 \max_{a,b} f(a,b) &= \max_a \max_b f(a,b) \\
 &= \max_a g(a) \\
 & \quad \text{where } g(a) = \max_b f(a,b)
 \end{aligned}$$

$$\begin{aligned}
 &= \max_{y \in \mathbb{R}_+} \left(\max_{x \in \mathbb{R}_+^{N-1}} p y - w \cdot x \right) \\
 & \quad \text{s.t. } f(x) = y \\
 &= \max_{y \in \mathbb{R}_+} p y + \left(\max_{x \in \mathbb{R}_+^{N-1}} -w \cdot x \right) \\
 & \quad \text{s.t. } f(x) = y \\
 &= \max_{y \in \mathbb{R}_+} p y - \left(\min_{x \in \mathbb{R}_+^{N-1}} w \cdot x \right) \\
 & \quad \text{s.t. } f(x) = y \\
 &= \max_{y \in \mathbb{R}_+} p y - c(y; w) \quad \square
 \end{aligned}$$

Theorem 2.4 $p = \underbrace{\frac{\partial c(y; w)}{\partial y}}_{\text{marginal cost}} \Big|_{y = y(p; w)}$

Proof Consider the Bellman equation

$$\pi(p; w) = \max_{y \in \mathbb{R}_+} Py - c(y; w).$$

The FOC w.r.t. y is

$$P = \frac{\partial c(y; w)}{\partial y} \Big|_{y = y(p; w)}$$

as required. \square

We can also apply the envelope theorem to the Bellman equation:

$$\frac{\partial \pi(p; w)}{\partial p} = \left[\frac{\partial}{\partial p} \{ Py - c(y; w) \} \right]_{y = y(p; w)}$$

$$= [y]_{y = y(p; w)}$$

$$= y(p; w)$$

and

$$\begin{aligned} \frac{\partial \pi(p; w)}{\partial w_i} &= \left[\frac{\partial}{\partial w_i} \{ Py - c(y; w) \} \right]_{y = y(p; w)} \\ &= \left[- \frac{\partial c(y; w)}{\partial w_i} \right]_{y = y(p; w)}. \end{aligned}$$

2.5 Upper Envelopes with Constraints

$$V(a) = \max_b v(a, b) \\ \text{s.t. } w(a, b) \geq 0$$

add a constraint

$$\text{Lagrangian: } L(a, b, \lambda) = v(a, b) + \lambda w(a, b).$$

~~Theorem~~ It's often true that

$$V(a) = \min_{\lambda} \max_b L(a, b, \lambda).$$

FOC w.r.t. b :

$$\left. \frac{\partial L(a, b, \lambda)}{\partial b} \right|_{b=b(a), \lambda=\lambda(a)} = 0$$

$$\Leftrightarrow \left[\frac{\partial v(a, b)}{\partial b} + \lambda \frac{\partial w(a, b)}{\partial b} \right]_{b=b(a), \lambda=\lambda(a)}$$

Theorem 2.5 (Constrained Envelope Theorem)

If V, v, w, b, λ are all differentiable functions, and the constraint binds at a ,

$$\text{then } V'(a) = \left[\frac{\partial v(a, b)}{\partial a} + \lambda \frac{\partial w(a, b)}{\partial a} \right]_{b=b(a), \lambda=\lambda(a)}$$

Proof (Chain rule proof).

$$v(a) = v(a, b(a)).$$

Lagrangian trick:

$$\begin{aligned} V(a) &= v(a, b(a)) + \lambda(a)w(a, b(a)) \\ &= L(a, b(a), \lambda(a)). \end{aligned}$$

Differentiating gives:

$$\begin{aligned} V'(a) &= \left[\frac{\partial L(a, b, \lambda)}{\partial a} + \frac{\partial L(a, b, \lambda)}{\partial b} b'(a) \right. \\ &\quad \left. + \frac{\partial L(a, b, \lambda)}{\partial \lambda} \cdot \lambda'(a) \right]_{b=b(a), \lambda=\lambda(a)} \end{aligned}$$

By the FOC, the circled bit is 0. \square